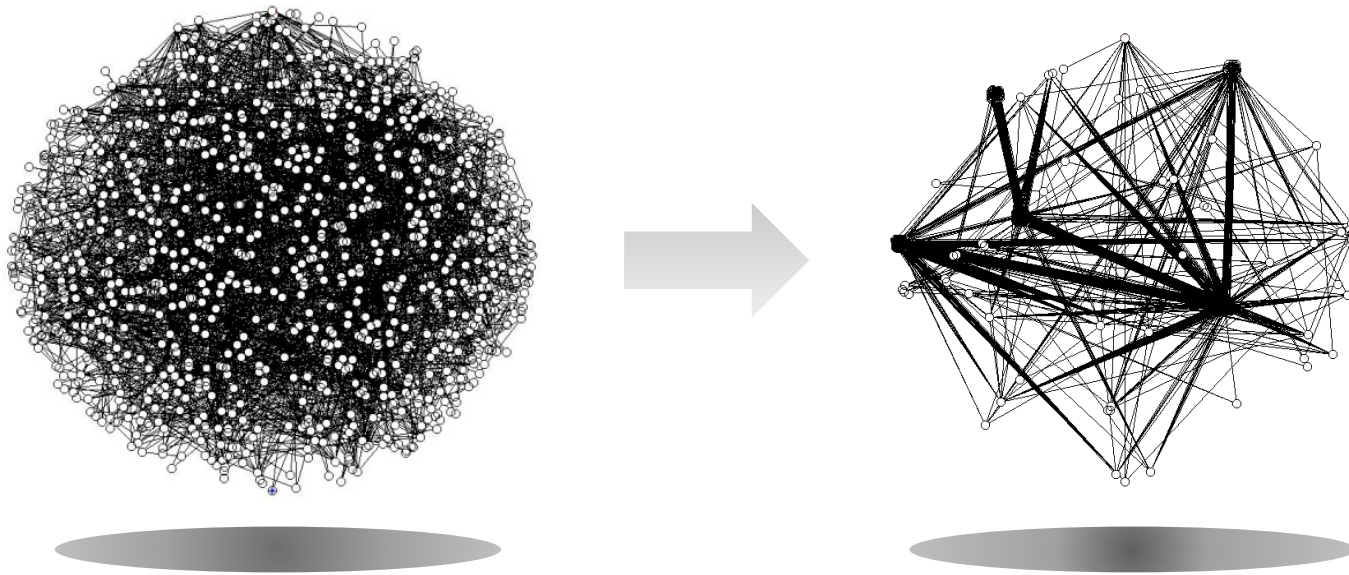


# Clustered Model Reduction of Interconnected Second-Order Systems and Its Applications to Power Systems



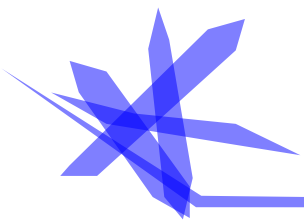
Takayuki Ishizaki, Jun-ichi Imura (Tokyo Inst. of Tech.)



# Outline

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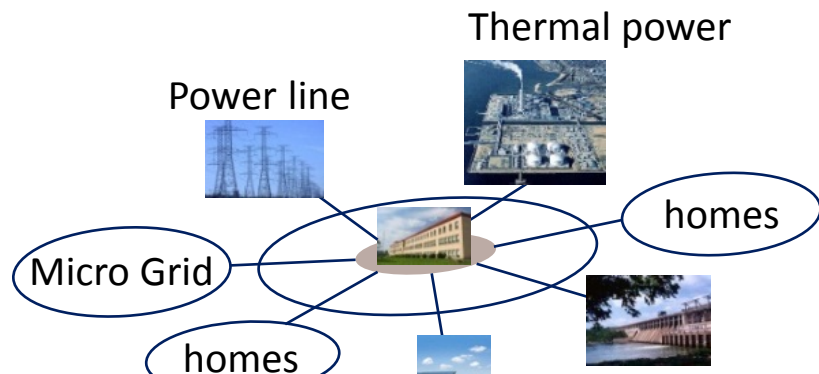
- ▶ Introduction: Why clustered model reduction?
- ▶ Clustered Model Reduction Theory
  - ▶ Interconnected first-order systems
  - ▶ Extension to second-order networks
- ▶ Application to power networks
- ▶ Conclusion



# Control of Large-Scale Networks

## Power Networks

- ▶ Tokyo area: **20 million** houses
  - ▶ **Instability** may be caused by renewables such as PV, wind

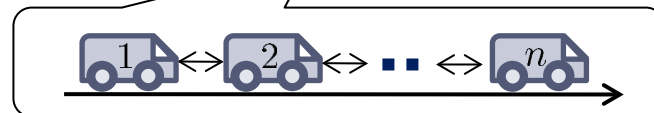


Model reduction is one prospective approach

- ▶ Center of Tokyo area: **5 million** cars
  - ▶ **Heavy traffic jam**



How to manage?





# Standard Model Reduction Framework

$$\begin{array}{ccc} \Sigma : \begin{cases} \dot{x} = Ax + Bu \\ y = Cx \\ x \in \mathbb{R}^n \end{cases} & \xrightarrow[\boxed{P} \in \mathbb{R}^{\hat{n} \times n}]{Px = \hat{x}} & \hat{\Sigma} : \begin{cases} \dot{\hat{x}} = PAP^\dagger \hat{x} + PBu \\ \hat{y} = CP^\dagger \hat{x} \\ \hat{x} \in \mathbb{R}^{\hat{n}}, \hat{n} < n \end{cases} \end{array}$$

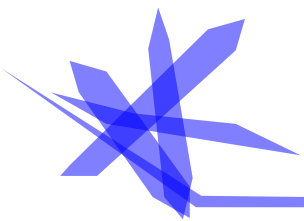
$\checkmark PP^\dagger = I_{\hat{n}}$

Main goal: Find  $P$  such that  $\|y - \hat{y}\|$  is small enough

+ stability of error systems, error analysis, low computation cost

Standard methods:

- ▶ Balanced truncation, Hankel norm approximation
  - ▶ error bound, stability preservation 😊 **high computational cost** 😞
- ▶ Krylov projection
  - ▶ lower computation cost 😊 **possibly unstable model, no error bound** 😞

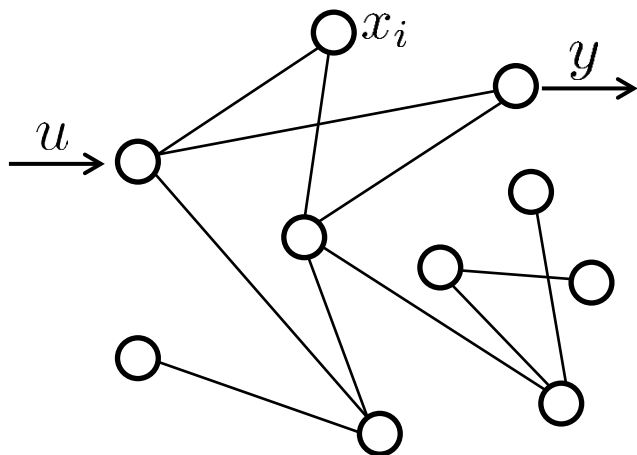


# Application of Standard Methods to Network Systems

**Drawback:** Network structure is lost through reduction

## Network system

$$\Sigma : \begin{cases} \dot{x} = Ax + Bu \\ y = Cx \end{cases}$$



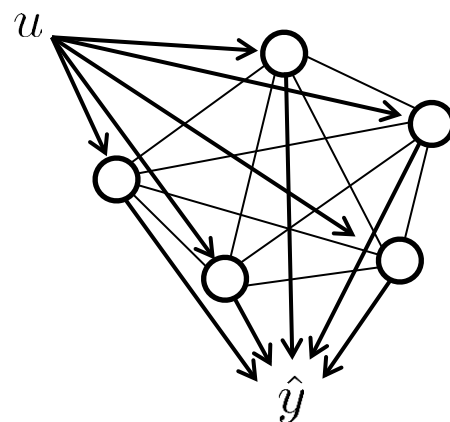
Sparse 😊

$$Px = \hat{x}$$
$$\xrightarrow{\quad}$$
$$P \in \mathbb{R}^{\hat{n} \times n}, \hat{n} < n$$

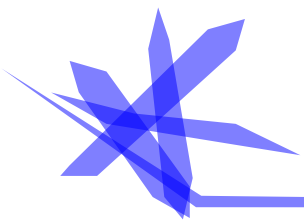
Dense matrix

## Reduced model

$$\hat{\Sigma} : \begin{cases} \dot{\hat{x}} = PAP^{\dagger} \hat{x} + PBu \\ \hat{y} = CP^{\dagger} \hat{x} \end{cases}$$



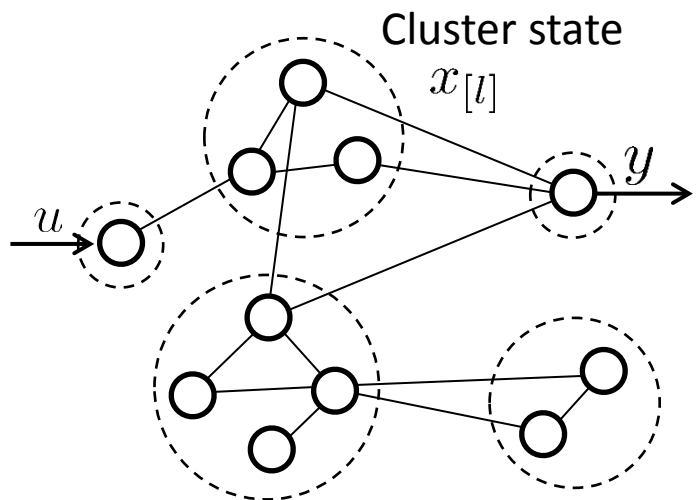
Dense 😞



# Clustered Model Reduction

## Network system

$$\Sigma : \begin{cases} \dot{x} = Ax + Bu \\ y = Cx \end{cases}$$



Sparse 😊

$$Px = \hat{x}$$

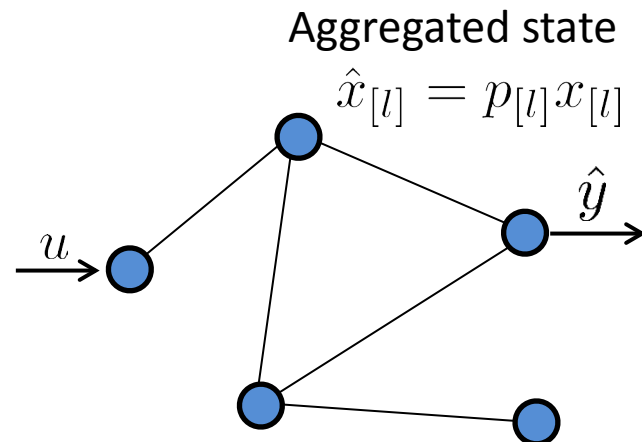


$p[l]$  : row vector

$$P = \begin{bmatrix} p[1] \\ p[2] \\ \vdots \end{bmatrix}$$

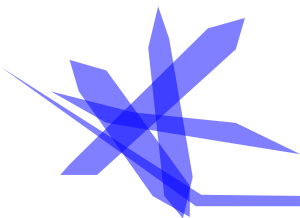
## Aggregated model

$$\hat{\Sigma} : \begin{cases} \dot{\hat{x}} = PAP^\dagger \hat{x} + PBu \\ \hat{y} = CP^\dagger \hat{x} \end{cases}$$



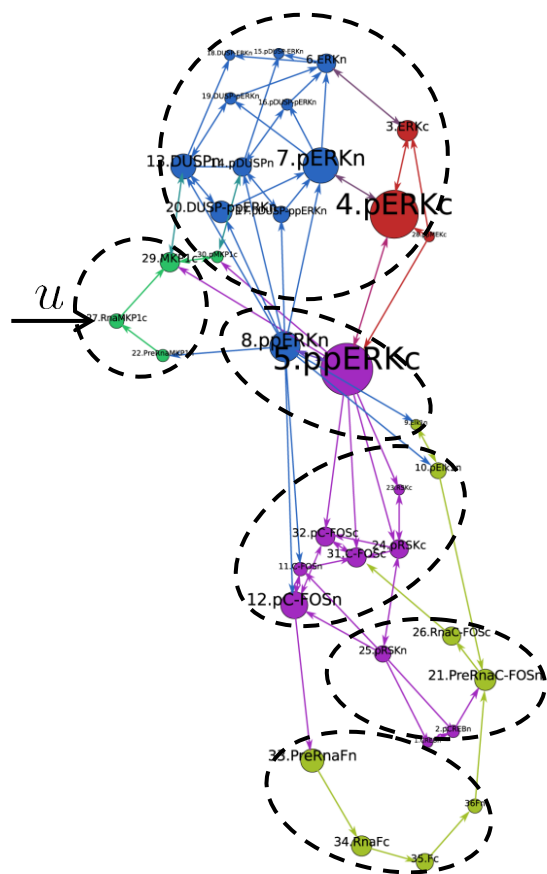
Sparse 😊

Preservation of network structure among **clusters**

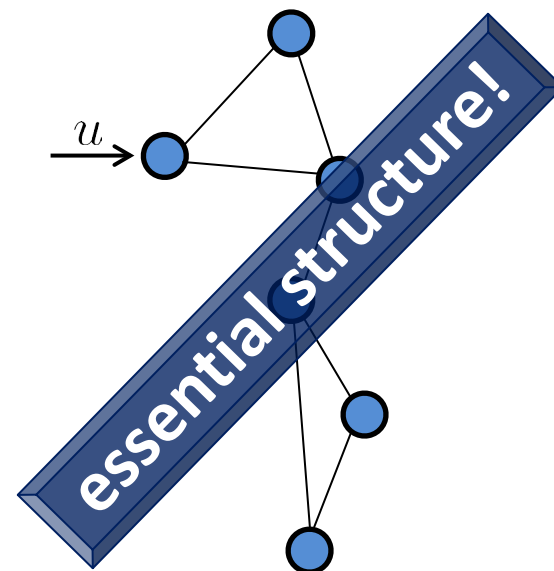
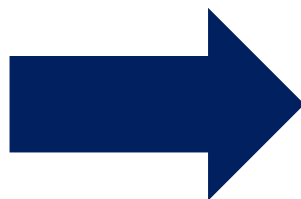


# Why Clustered Model Reduction?

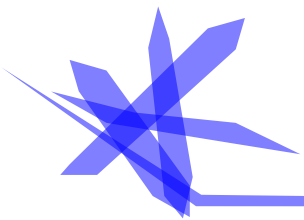
Gene Network [Mochizuki et al. , J. Theoretical Biology (2010)]



Clustered model reduction



Extract essential structure  
to study mechanism of functions

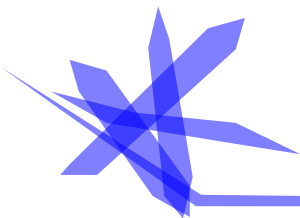


# Outline

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- ▶ Introduction: Why clustered model reduction?
- ▶ **Clustered Model Reduction Theory**
  - ▶ **Interconnected first-order systems**
  - ▶ Extension to second-order networks
- ▶ Application to power networks
- ▶ Conclusion



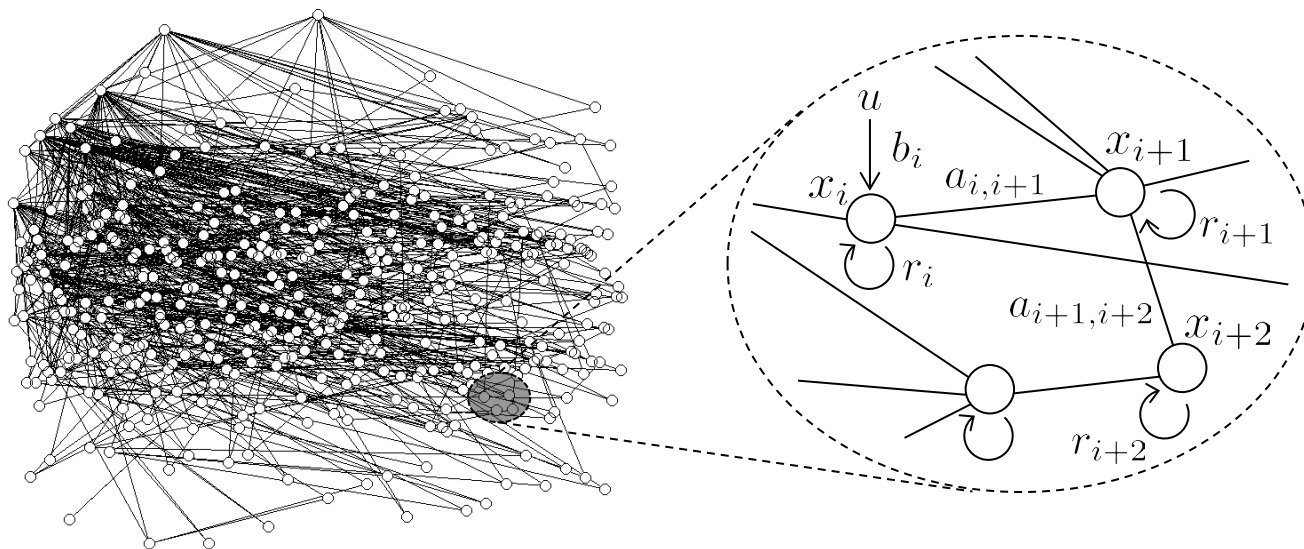


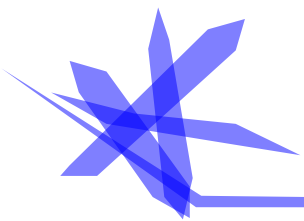
# System Description (First-Order Subsystems)

## [Definition] Bidirectional Network

$\dot{x} = Ax + Bu$  with  $A = \{a_{i,j}\} \in \mathbb{R}^{n \times n}$  and  $B = \{b_i\} \in \mathbb{R}^n$  is said to be bidirectional network if  $A$  is **symmetric** and **stable**.

Reaction-diffusion systems:  $\dot{x}_i = -r_i x_i + \sum_{j=1, j \neq i}^n a_{i,j} (x_j - x_i) + b_i u$





# Clustered Model Reduction Problem

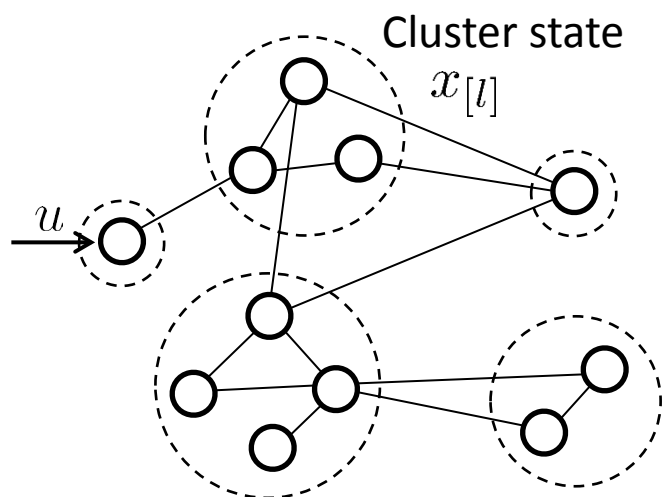
**[Problem]** Given  $\epsilon \geq 0$ , find a **cluster set**  $\{\mathcal{I}_{[l]}\}_{l \in \mathbb{L}}$  such that

$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty} \leq \epsilon$$

where  $g(s) := (sI_n - A)^{-1}B$  and  $\hat{g}(s) := P^\top (sI_{\hat{n}} - PAP^\top)^{-1}PB$ .

## Bidirectional network

$$\Sigma : \dot{x} = Ax + Bu$$



Sparse 😊

$$Px = \xi$$

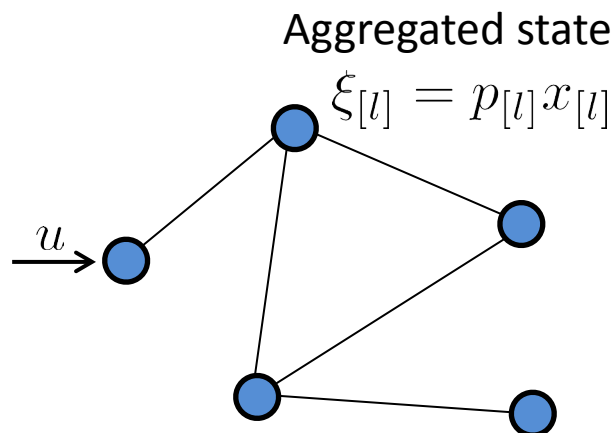


$$P = \text{Diag}(p_{[1]}, \dots, p_{[\hat{n}]})$$

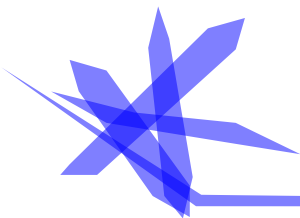
$$p_{[l]} = \frac{1}{\sqrt{|\mathcal{I}_{[l]}|}} \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix}^\top$$

## Aggregated model

$$\hat{\Sigma} : \begin{cases} \dot{\xi} = PAP^\top \xi + PBu \\ \hat{x} = P^\top \xi \end{cases}$$

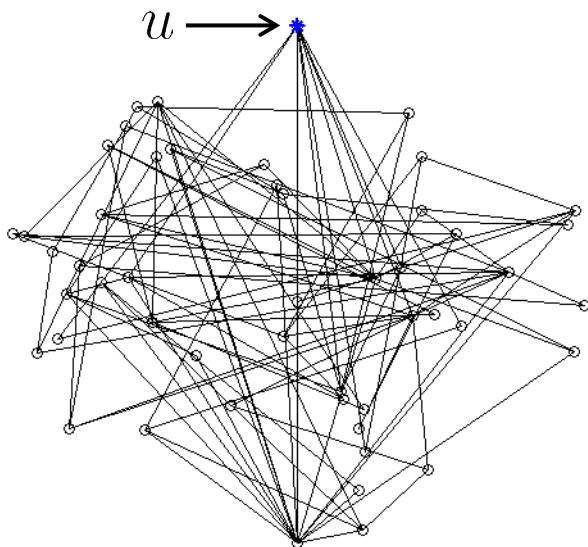


Sparse 😊



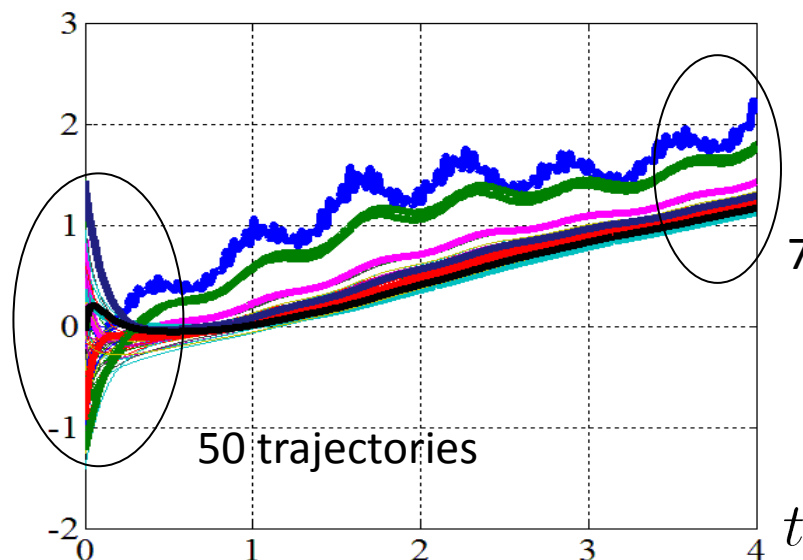
# How to Formulate Reducibility?

Bidirectional network  $\dot{x} = Ax + Bu$



50 nodes, nonzero  $a_{i,j}$  is randomly chosen from  $(0, 1]$

[State trajectory under random  $u$ ]



7 clusters

$$x_i(t) - x_j(t) \equiv 0, \quad \forall u(t)$$

**Local uncontrollability!**

## [Definition] Reducible cluster

A cluster  $\mathcal{I}_{[l]}$  is said to be reducible if under **any input signal**  $u(t)$

$$x_i(t) \equiv x_j(t), \quad \forall i, j \in \mathcal{I}_{[l]}.$$





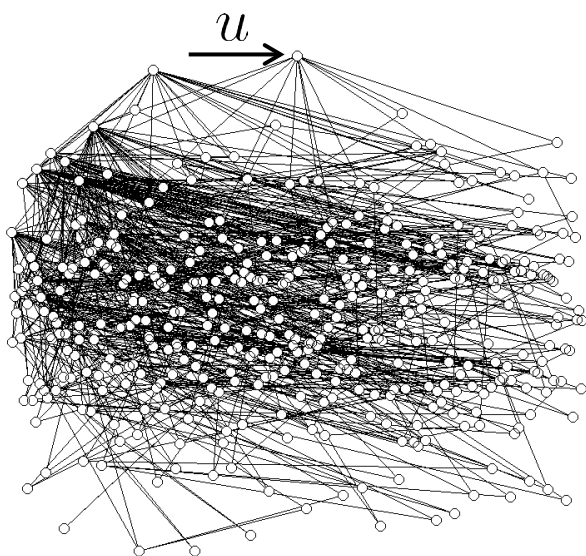
# Positive Tridiagonalization

**[Lemma]** For every bidirectional network  $(A, B)$ , there exists a unitary  $H \in \mathbb{R}^{n \times n}$  such that  $(\tilde{A}, \tilde{B}) = (H^T A H, H^T B)$  has the following structure.

Bidirectional network  $(A, B)$

$$\dot{x} = Ax + Bu, \quad A = A^T$$

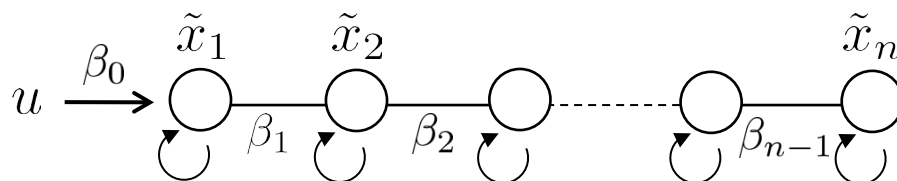
(not necessarily positive)



$$x = H\tilde{x}$$



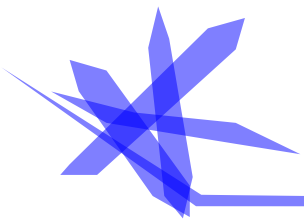
**Positive** tridiagonal realization  $(\tilde{A}, \tilde{B})$



$$\tilde{A} = \begin{bmatrix} \alpha_1 & \beta_1 & & & \\ \beta_1 & \alpha_2 & \beta_2 & & \\ & \ddots & \ddots & \ddots & \\ & & \ddots & \ddots & \beta_{n-1} \\ & & & \beta_{n-1} & \alpha_n \end{bmatrix} \quad \tilde{B} = \begin{bmatrix} \beta_0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

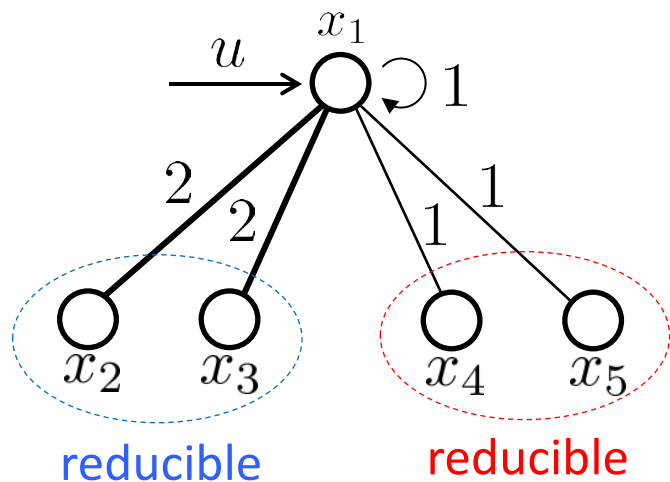
Metzler

$$\checkmark \quad \beta_i \geq 0$$



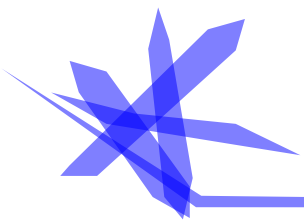
# Reducibility Characterization

Bidirectional network  $(A, B)$



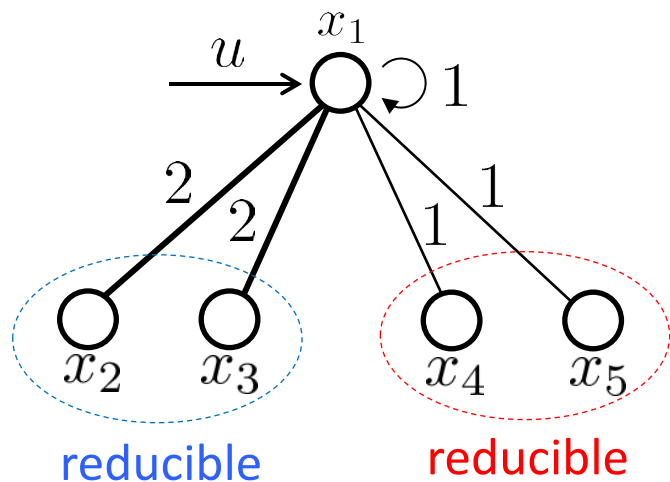
$$A = \begin{bmatrix} -(6 + \textcolor{teal}{1}) & 2 & 2 & 1 & 1 \\ 2 & -2 & 0 & 0 & 0 \\ 2 & 0 & -2 & 0 & 0 \\ 1 & 0 & 0 & -1 & 0 \\ 1 & 0 & 0 & 0 & -1 \end{bmatrix} \quad B = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$

— (graph Laplacian +  $\textcolor{teal}{\text{diagonal}}$ )



# Reducibility Characterization

Bidirectional network  $(A, B)$



$$\begin{cases} (\tilde{A}, \tilde{B}) : \text{positive tridiagonal realization} \\ H : \text{transformation matrix} \end{cases}$$

Index matrix

$$\Phi := H \text{diag}(-\tilde{A}^{-1} \tilde{B})$$

Characterization in frequency domain

$$\Phi = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0 & 1.20 & -0.20 & 0 & 0 \\ 0 & 1.20 & -0.20 & 0 & 0 \\ 0 & 0.60 & 0.40 & 0 & 0 \\ 0 & 0.60 & 0.40 & 0 & 0 \end{bmatrix}$$

} identical  
} identical



Equivalent characterization of cluster reducibility



# $\theta$ -Reducible Cluster Aggregation

## [Definition] $\theta$ -Reducibility of Clusters

A cluster  $\mathcal{I}_{[l]}$  is said to be  $\theta$ -reducible if

$$\|\text{row}_i[\Phi] - \text{row}_j[\Phi]\|_{l_\infty} \leq \theta, \quad \forall i, j \in \mathcal{I}_{[l]}$$

$$x_i(t) - x_j(t) \simeq 0, \quad \forall u(t)$$

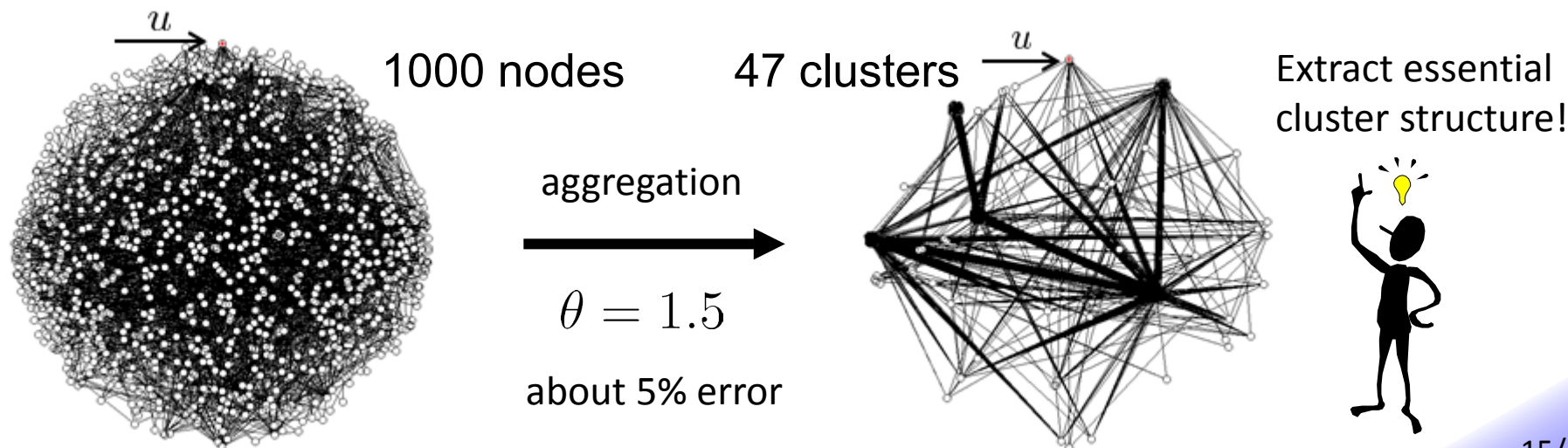
Similar behavior

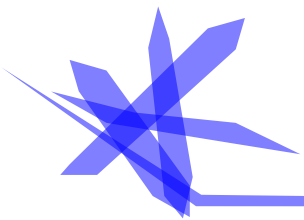
[Theorem] If all clusters are  $\theta$ -reducible, then

$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty} \leq \gamma \sqrt{\sum_{l=1}^{\hat{n}} |\mathcal{I}_{[l]}| (|\mathcal{I}_{[l]}| - 1) \theta}$$

where  $\gamma := \|(PAP^\top)^{-1}PA\|$ .

$\theta$ : coarseness parameter





# Outline

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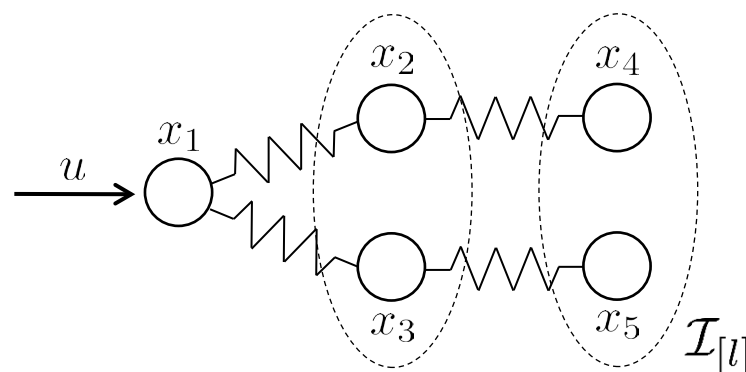




# Formulation by Second-Order Systems

## Second-order networks

$$\Sigma : \ddot{x} + D\dot{x} + Kx = fu$$

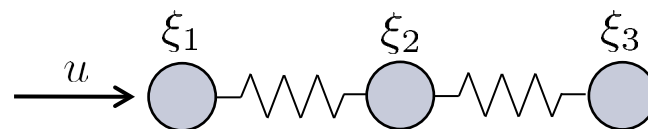


$$Px = \xi$$



## Aggregated model

$$\hat{\Sigma} : \begin{cases} \ddot{\xi} + PDP^T\dot{\xi} + PKP^T\xi = Pfu \\ \hat{x} = P^T\xi \end{cases}$$



[Problem] Given  $\epsilon \geq 0$ , find a **cluster set**  $\{\mathcal{I}_{[l]}\}_{l \in \mathbb{L}}$  such that

$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_{\infty}} \leq \epsilon$$

where  $g(s) := (s^2 I_n + sD + K)^{-1}f$  and  $\hat{g}(s) := P^T(s^2 I_{\hat{n}} + sPDP^T + PKP^T)^{-1}Pf$ .



# Extension to Second-Order Networks

First-order representation (2n-dim. system) ✓  $X := \begin{bmatrix} x \\ \dot{x} \end{bmatrix}$

$$\Sigma : \begin{cases} \dot{X} = AX + Bu \\ x = CX \end{cases} \quad \text{where} \quad A := \begin{bmatrix} 0 & I_n \\ -K & -D \end{bmatrix} \quad B := \begin{bmatrix} 0 \\ f \end{bmatrix} \quad C := \begin{bmatrix} I_n & 0 \end{bmatrix}$$

Index matrix  $\Phi = \begin{bmatrix} \Phi_1 \\ \Phi_2 \end{bmatrix} \in \mathbb{R}^{2n \times 2n}$  w.r.t.  $\begin{cases} \text{position } x \\ \text{velocity } \dot{x} \end{cases}$

**[Definition]** A cluster  $\mathcal{I}_{[l]}$  is said to be  $\theta$ -reducible if

$$\|\text{row}_i[\Phi_k] - \text{row}_j[\Phi_k]\|_{l_\infty} \leq \theta, \quad \forall i, j \in \mathcal{I}_{[l]}, \quad k \in \{1, 2\}$$

**[Theorem]** If all clusters are  $\theta$ -reducible, then

$$\|g(s) - \hat{g}(s)\|_{\mathcal{H}_\infty} \leq \gamma \sqrt{\sum_{l=1}^{\hat{n}} |\mathcal{I}_{[l]}| (|\mathcal{I}_{[l]}| - 1) \theta}$$

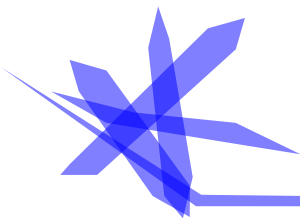
where  $\gamma := \sqrt{2} \|P(s^2 I_{\hat{n}} + sPDP^\top + PKP^\top)^{-1} [PK \quad PD] - [I_n \quad 0]\|_{\mathcal{H}_\infty}$ .



# Outline

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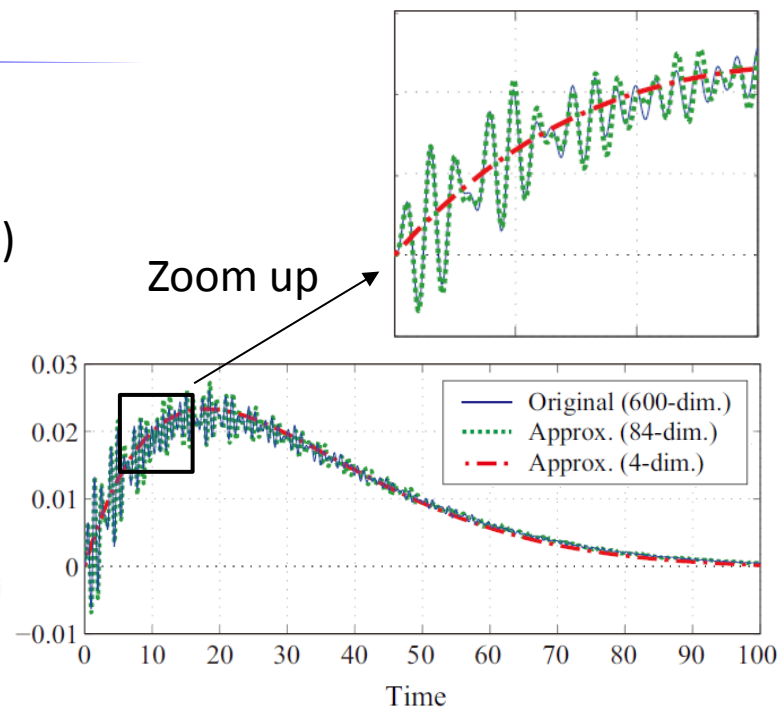
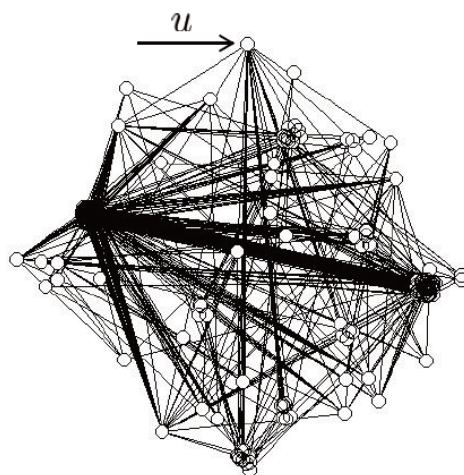
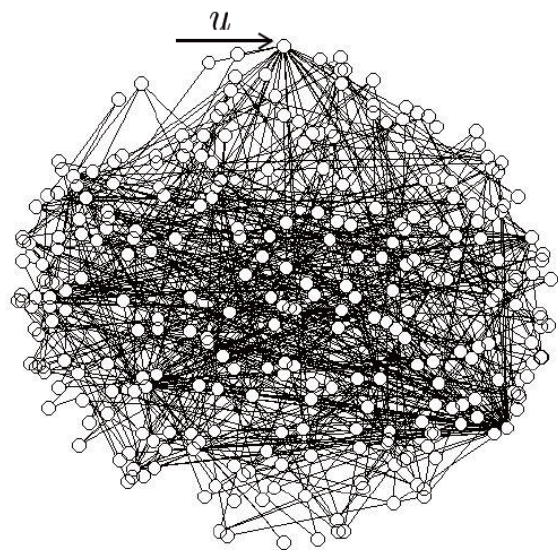
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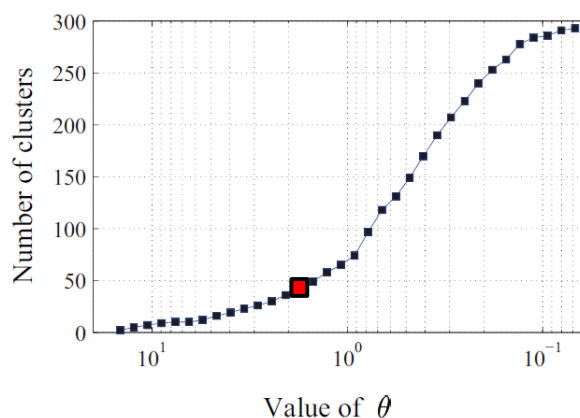
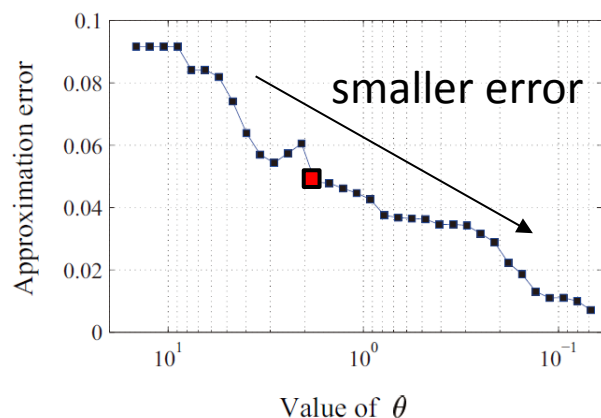
# Numerical Example

## Power network modeled by swing equation

Original network (300 nodes)    Agg. model (42 clusters)



Position trajectory of a mass



Relative error

$$\frac{\|g(s) - \hat{g}(s)\|_{\mathcal{H}_{\infty}}}{\|g(s)\|_{\mathcal{H}_{\infty}}} = 4.81\%$$

when  $\theta = 1.76$



# Concluding Remarks

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- ▶ Clustered model reduction
  - ▶ extract essential information on input-to-state mapping
  - ▶ application to power networks model by swing equation
- ▶ Future works
  - ▶ application to more realistic power networks
  - ▶ extension to nonlinear systems
  - ▶ application to control system design

[T. Ishizaki et al. IEEE TAC (2014)], [T. Ishizaki et al. NOLTA (2015)], My website, etc.

## Thank you for your attention!